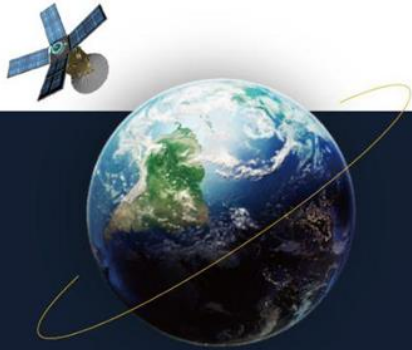


Tensor Tech Co., Ltd.

First Commercial Spherical Motor for
Spacecrafts and beyond



Motion Control Solutions, Assembled by Standard Product & Services:

2024
Brochure

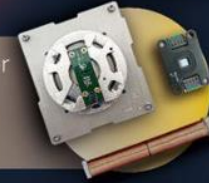
Business Model

Integrated ADCS for NanoSat
Integrated ADCS for SmallSat



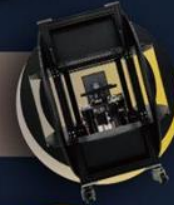
System

CMG based on Spherical Motor
Sun Sensor
Magnetorquer



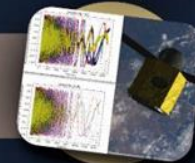
Component

ADCS Testbed
Attitude Determination Test Platform



Equipment

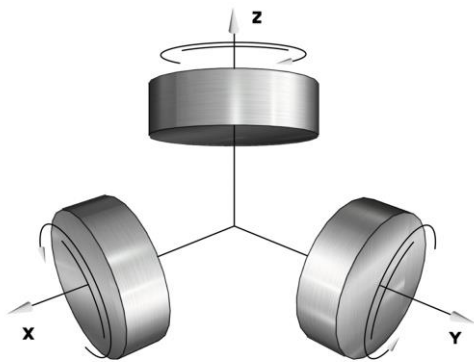
ADCS Test Services
Constellation Motion Control



Service

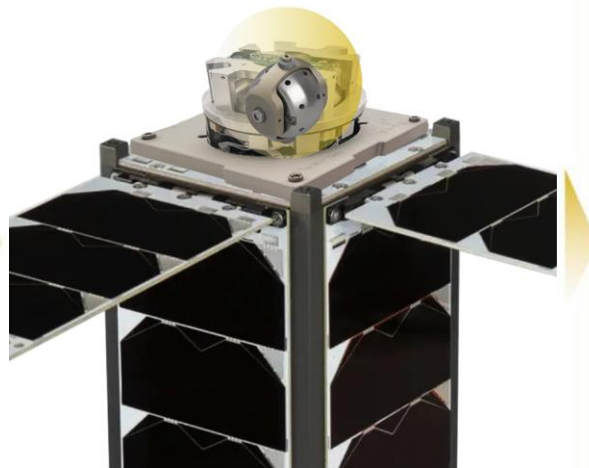
Past

3 X Single-axis Electric Motors



Now

One Spherical Motor



Killer Application:
Constellation Motion Control Service

Enabling

- Formation Flying
- Satellite-to-Satellite Pointing
- Collision Avoidance



- One motor, that does the job of several
- Offers **X2** volume and mass budget for payload, maximizing profitability of space assets.
- Serving as a Control Moment Gyro (CMG). Offers **X10** torque-to-power ratio, such agility enables the constellation motion control.

Open-loop Gyroscopic Torque Exertion by SGCMG



Founded in 2020

First Flight Heritage Achieved in Jan 2022

- 2.5M USD Raised to Date
- 4 Granted Invention Patents, 3 Pending Applications
- 20+ Clients Worldwide, Served by 2 Offices:



Traction

Clients

Commercial



Government



Academic



Business Development & Sales

2880 ZANKER ROAD, SUITE 103,
SAN JOSE, CA 95134, U.S.A.



System Research & Development

10F., NO. 33, CHENGTIAN RD.,
TUCHENG DIST.,
NEW TAIPEI CITY 236039,
TAIWAN (R.O.C.)





Thank you for your time!

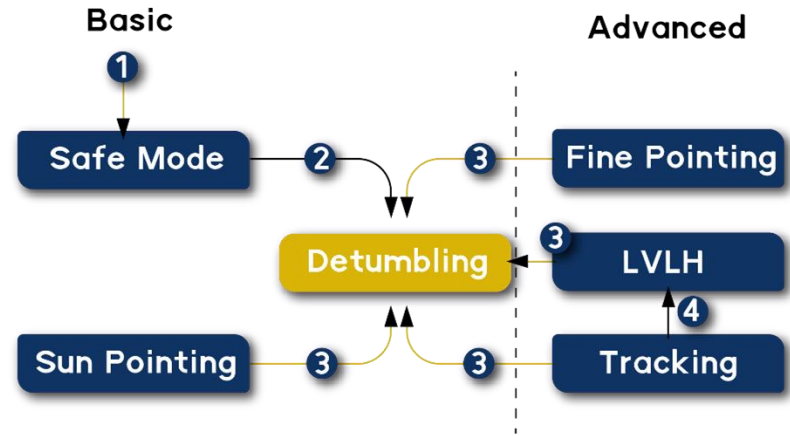
See some more Technical
Intros below:



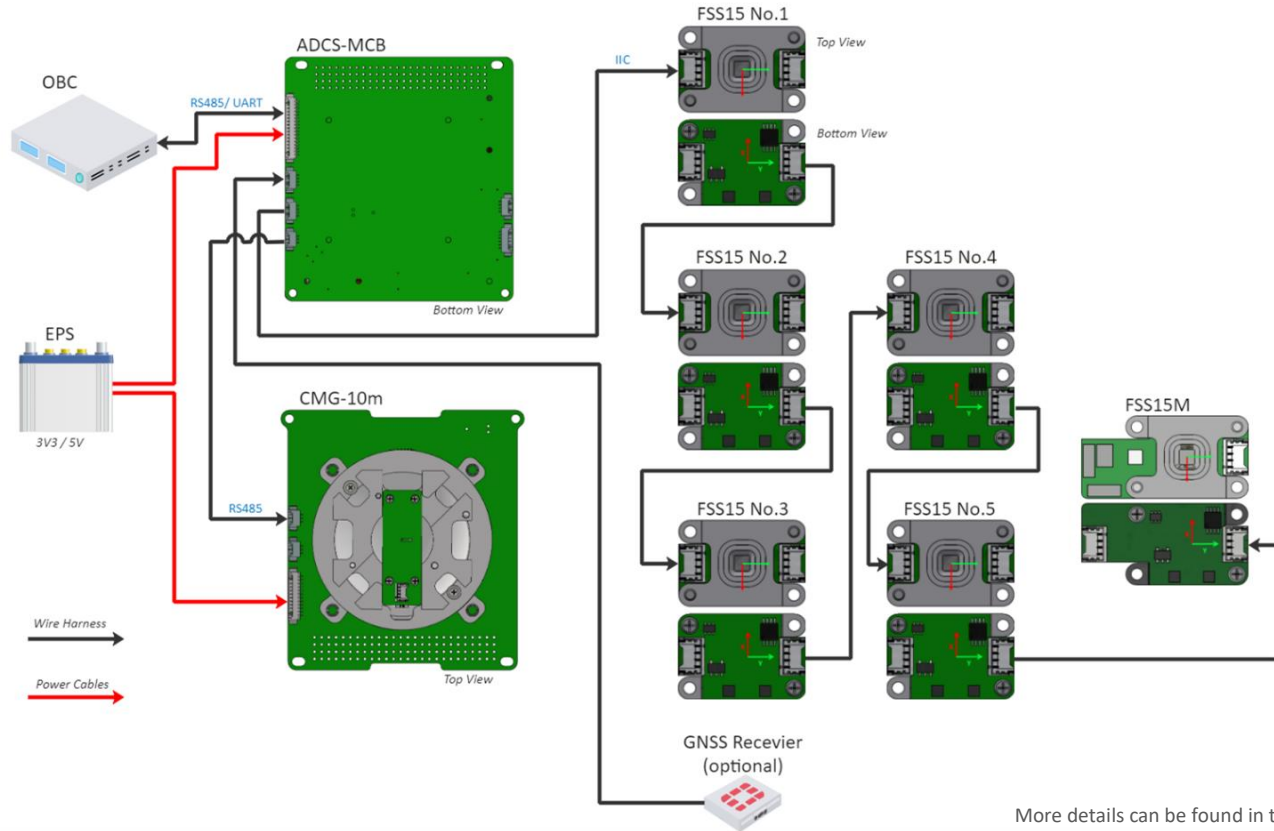
together we go further

Integrated ADCS with Automatic Modes

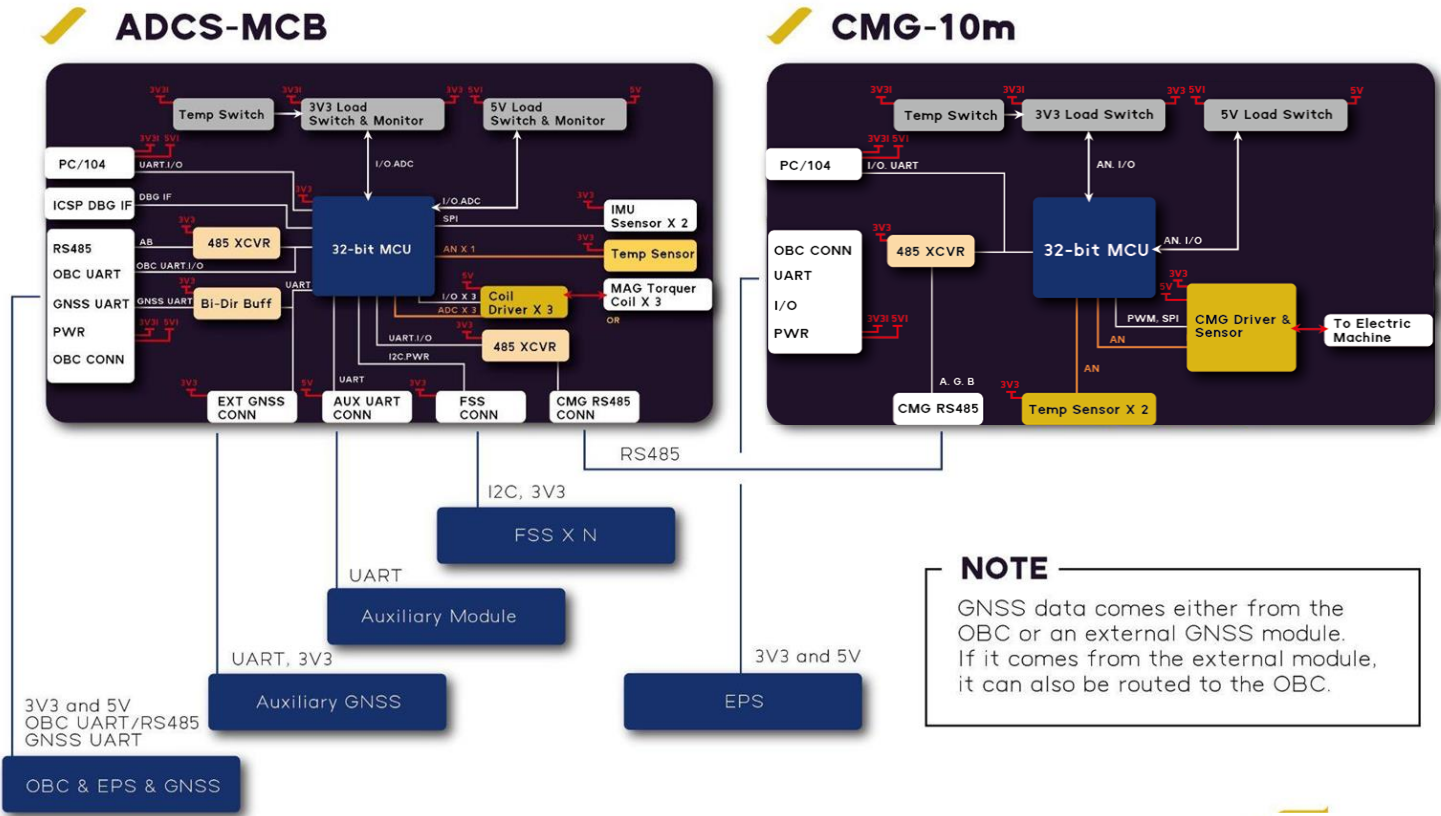
- Condition ①: Soft Error or tumbling rate > 360 deg/second
- Condition ②: Tumbling rate between 5 deg/second to 360deg/second and rotor speed > 5 rpm
- Condition ③: Tumbling rate > 5 deg/second
- Condition ④: Target lost



Wiring Guidelines



Electrical Connection Diagram

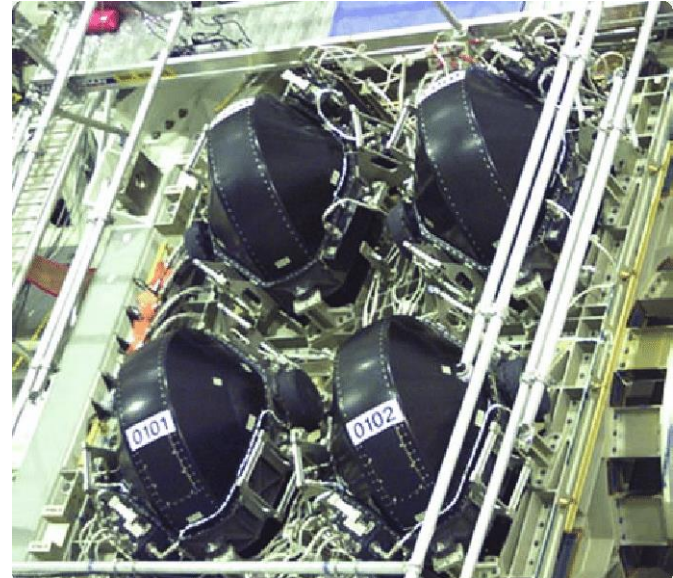


CMG Applications - Agile Satellites (WorldView 2-3-4, Pléiades, Spot 5-6-7, etc) and Large Spacecrafts (Space Stations)

Maxar's World View
(Remote Sensing)



International Space Station

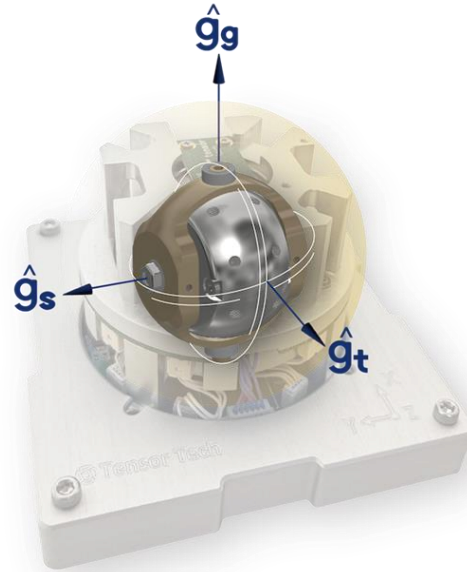


Principle of Single-gimbal Control Moment Gyro (CMG)

$$\tau_s = I_s \dot{\omega}_s$$

$$\tau_t = I_s \omega_g \omega_s$$

$$\tau_g = I_g \dot{\omega}_g$$



Attitude & Heading Reference System (AHRS) Architecture for Antenna Control Unit (ACU)



1

AHRS with Better Accuracy:

- Smaller Uncertainty Cone,
- Shorter Searching Time

2

AHRS integrate with ACU

- Better Stability for Long Term Tracking
- Design for Specific Application

3

Inter-satellite Link:

- Position Propagation of the Target Satellite;
Calculate the required beam angles

DynaSense

Introducing Tensor Tech's DynaSense
Advanced AHR5 for Satellite Ground Equipment



Yaw: -8.89765, Pitch: -28.13080, Roll: -48.28131
From Sensors to math.

tensortech.co